Shattering All Sets of k Points in "General Position" Requires (k - 1)/2 Parameters

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For classes of concepts defined by certain classes of analytic functions depending on *n* parameters, there are nonempty open sets of samples of length 2n + 2 that cannot be shattered. A slightly weaker result is also proved for piecewise-analytic functions. The special case of neural networks is discussed.

1 Introduction _

The generalization capabilities of neural networks are often quantified in terms of the maximal number of possible binary classifications that could be obtained, by means of weight assignments, on any given set of input patterns. Obviously the larger the number of such potential classifications, the lower the predictability that is possible on the basis of a partial assignment ("loading of training data") already achieved. Thus, it is of interest to obtain useful upper bounds on this number and in particular to study the Vapnik-Chervonenkis (VC) dimension, which is the size of the largest set of inputs that can be shattered (arbitrary binary labeling is possible). Recent results (cf. Koiran and Sontag in press and also Maass 1994 for closely related work and a survey) show that the VC dimension grows at least as fast as the square n^2 of the number of adjustable weights n in the net, and this number might grow as fast as n^4 (Karpinski and Macintyre in press). These results are quite pessimistic, since they imply that the number of samples required for reliable generalization, *in the sense of PAC learning*, is very high.

On the other hand, it is conceivable that those sets of input patterns that can be shattered are all in some sense "special" and that if we ask instead, as done in the classical literature in pattern recognition, for the shattering of *all sets in "general position"* (e.g., Cover's work on capacity of perceptrons, Cover 1988), then an upper bound of O(n) might hold. Strong evidence for this possibility was provided by Adam Kowalczyk (in press), who showed that this indeed happens for the (very special) case of hard-threshold neural networks with a fully connected first layer. In this article, I establish a linear upper bound for arbitrary sigmoidal (as well as threshold) neural nets, proving that in that sense, the perceptron results can be recovered in a strong sense (up to a factor of two).

There is potential relevance of the results to variations of PAC learning when one weakens the requirement that generalization capabilities must hold with respect to all possible input distributions; this will be the subject of future work. The estimate is also useful in the very different context of understanding computational abilities; as an illustration, note that the main result is being employed by Maass (in press) for contrasting the computational power of spiking neurons (Maass 1996) with that of sigmoidal neural networks.

1.1 Parametric Classes, Shattering. Assume given two positive integers *n* and *m* and a function

 $\beta: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}.$

In this context we will call *n* the number of parameters, elements of \mathbb{R}^n parameter vectors (or weights), *m* the input dimension, elements of \mathbb{R}^m input vectors, and β a response function. We think of $\beta(x, u)$ as a function of the inputs *u* for each parameter vector *x*. For each integer *k*, a *k*-tuple of the form

$$\vec{u} = (u_1, \ldots, u_k) \in (\mathbb{R}^m)^k = \mathbb{R}^{mk}$$

will be called an (ordered) sample of length k.

We want to measure how rich the set of functions $\{\beta(x, \cdot), x \in \mathbb{R}^n\}$ is for binary classification purposes. Consider a sample $\vec{u} = (u_1, \ldots, u_k)$ of length *k*. A sequence $\vec{\varepsilon} = (\varepsilon_1, \ldots, \varepsilon_k) \in \{-1, 1\}^k$ will be said to be *assignable* to \vec{u} (with respect to the given response function) if there exists some parameter vector *x* so that

 $\operatorname{sign}\left(\beta(x, u_i)\right) = \varepsilon_i, i = 1, \ldots, k,$

where we are defining sign (y) = 1 if y > 0 and -1 otherwise. We will say here that a sample \vec{u} of length k is \pm -shattered (by β) if, for each $\vec{\varepsilon} \in \{-1, 1\}^k$, either $\vec{\varepsilon}$ or $-\vec{\varepsilon}$ is assignable to \vec{u} .

For each *k*, let S_k be the subset of $(\mathbb{R}^m)^k = \mathbb{R}^{mk}$, possibly empty, consisting of those samples that are \pm -shattered. We define

$$\mu = \mu_{\beta} := \sup \left\{ k \ge 1 \mid S_k \text{ is a dense subset of } \mathbb{R}^{mk} \right\}.$$

Our goal is to show that under reasonable assumptions on β , necessarily $\mu \leq 2n + 1$.

The organization of this article is as follows. Section 2 discusses the precise statement of the result, for functions β that are analytic and "definable" as well as the fact that this bound is optimal. Section 3 provides a proof of the result, which is based on material on analytic functions and especially on new results from the theory of exponentials, which are reviewed briefly in the Appendix. Section 4 shows how to generalize the result to the piecewise analytic definable case, which allows the consideration of neural networks with discontinuous activation functions.

2 Precise Statements and Remarks

Note that 2n+1 is the best possible upper bound, assuming that one wants to prove a result that includes at least all polynomially parameterized classes. To show this, we must exhibit for each integer n > 0 a polynomial response function β : $\mathbb{R}^n \times \mathbb{R}^{m_n} \to R$ with the property that S_{2n+1} is dense in \mathbb{R}^{2n+1} . In fact, we give, for each n, a β with $m_n = 1$ so that *every* sample of length 2n+1 consisting of distinct vectors can be \pm -shattered:

$$\beta((x_1,\ldots,x_n),u) := (u-x_1)^2 (u-x_2)^2 \ldots (u-x_n)^2.$$

Take any $\vec{u} \in \mathbb{R}^{2n+1}$ with all u_i distinct. The claim is that this is \pm -shattered. Indeed, pick any $\vec{\varepsilon} = (\varepsilon_1, \ldots, \varepsilon_{2n+1}) \in \{-1, 1\}^{2n+1}$. Without loss of generality, we assume that there are $s \leq n$ elements "-1" in the sequence $\vec{\varepsilon}$ (otherwise, we assign $-\vec{\varepsilon}$ instead) and these are $\varepsilon_{i_1}, \ldots, \varepsilon_{i_s}$. Let $x_j := u_{i_j}$ for $j = 1, \ldots, s$ and pick x_{s+1}, \ldots, x_n to be any elements not in the set $\{u_1, \ldots, u_{2n+1}\}$. We have that $\beta(x, u) = 0$ for each $u = u_{i_j}, j = 1, \ldots, s$, and $\beta(x, u) > 0$ for all other $u \in \mathbb{R}$. Thus sign $(\beta(x, u_i)) = \varepsilon_i$ for all i.

The question we address next is what are "reasonable" assumptions on the class β so that an upper bound like 2n+1 holds. It is not difficult to see that merely asking β to be an analytic function is not sufficient even to guarantee finiteness. This is illustrated trivially by the example $\beta(x, u) = \sin(xu)$, which has n = m = 1 but for which $\mu_{\beta} = +\infty$ (this is a consequence of the fact that if the numbers u_1, \ldots, u_k, π are linearly independent over the rationals, then the set of vectors $(\sin(\ell u_1), \ldots, \sin(\ell u_k))$, as ℓ ranges over the positive integers, is a dense subset of $[-1, 1]^k$). In fact, it is possible to define a fixed analytic function β , with m = 1, for which S_k consists of all sequences of k distinct elements of \mathbb{R} , not merely dense in \mathbb{R}^{km} , for all k (see Sontag 1992).

Thus, analyticity is in itself not enough to obtain nontrivial bounds. We will assume that β is analytic and *definable*. The Appendix recalls the definition and basic facts about ("exp-RA") definable functions. Informally, these are functions that can be defined in terms of any first-order logic sentence built out of the standard propositional connectives, existential and universal quantification, and which involve rational operations and exponentiation. (Also allowed in the formulas are certain restricted analytic functions, for instance, arctan(*x*), but sin(*x*) is not included.) In particular—and this is of interest in the context of applications to "artificial neural networks"—any response of a "multilayer sigmoidal network" with "activation function" $1/(1 + e^{-x})$ is definable in this sense because it is obtained by iterative compositions and polynomial combinations involving the activation function, which in turn is constructed by means of rational operations involving exponentiation.

Theorem 1. If β : $\mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$ is an analytic definable response, then $\mu_\beta \leq 2n+1$.

This result is proved in the next section.

Remark 2.1. In computational learning theory, one defines *shattering* of a sample \vec{u} by the requirement that each $\vec{\varepsilon}$ be assignable, and studies the set S_k^+ consisting of all those samples that are shattered. For our results, it seems more natural to look at \pm -shattering because we then obtain a bestpossible bound. In any case, the two concepts are almost identical. Since $S_k^+ \subseteq S_k$ for all *k*, the upper bound 2n + 1 will also apply in particular to $\sup_{k} \{k \ge 1 | S_k^+ \text{ is a dense subset of } \mathbb{R}^{km} \}$. (Conversely, if \vec{u} can be \pm -shattered, then the new response function with n + 1 parameters, and defined for parameters vectors $(x_0, x_1, \ldots, x_n) \in \mathbb{R}^{n+1}$ by $\beta_0((x_0, x), u) := 1 - x_0 \beta(x, u)$, shatters the same sample \vec{u} .) In learning theory and statistical estimation, the Vapnik-Chervonenkis (VC) dimension is defined as the supremum of the integers k such that S_k^+ is nonempty; here we are asking questions regarding shattering of arbitrary sets of points in "general position," a concept that appears in Cover's and in other classical pattern recognition work. For the best-known (obviously larger) upper bounds for VC dimension, for closely related classes of responses, see Karpinski and Macintyre (in press) and see also Maass (1994) and Koiran and Sontag (1996) for superlinear lower bounds.

3 Proof of Main Result _

We need to show that if $k \ge 2n + 2$ then S_k is not dense; that is, there is some nonempty open subset $Q \subseteq \mathbb{R}^{mk}$ so that $Q \bigcap S_k = \emptyset$. It will be enough to show this when k = 2n + 2. In fact, we will establish a much stronger fact: for each nonempty open subset $W_0 \subseteq \mathbb{R}^{m(n+1)}$, there is a nonempty open subset $Q \subseteq W_0^2$ such that $Q \bigcap S_{2n+2} = \emptyset$.

For any integer ℓ , we introduce the following subset of $\mathbb{R}^{m\ell}$:

$$A_{\ell} := \{(u_1,\ldots,u_{\ell}) \mid \exists x \operatorname{st} \beta(x,\cdot) \neq 0, \beta(x,u_1) = \cdots = \beta(x,u_{\ell}) = 0\}.$$

By corollary A.1, it follows that A_{ℓ} has a dimension strictly less than $m\ell$ whenever $\ell = n + 1$. The content of that lemma is totally intuitive: for each fixed *x*, except those for which the map $\beta(x, u)$ is identically zero, the set of u_1 's so that $\beta(x, u_1) = 0$ is of dimension at most m - 1 (since this set is the set of zeroes of a nontrivial analytic function); and similarly for each of u_2 , \ldots , u_{ℓ} . Thus, for each such *x*, the Cartesian product of these sets, namely, the set of vectors (u_1, \ldots, u_{ℓ}) so that $\beta(x, u_1) = \cdots = \beta(x, u_{\ell}) = 0$, has dimension at most $\ell(m-1)$. If we now let *x* range over the whole parameter space \mathbb{R}^n (but not including those *x* for which $\beta(x, \cdot) \equiv 0$), the set A_{ℓ} is obtained as a union of an *n*-parameter family of sets, each of which is of dimension $\leq \ell(m-1)$, from which it follows that A_{ℓ} has dimension at most

 $n + \ell(m-1)$, which is less than $m\ell$ provided $\ell = n + 1$. The technicalities have to do only with defining precisely the meaning of "dimension"—this will mean the maximum possible dimension of a submanifold of the setand establishing the obvious formulas, such as the fact that the union of an *n*-parameter family of sets of dimension $\leq s$ has dimension $\leq n + s$.

Let W_0 be any open subset of $\mathbb{R}^{m(n+1)}$. The fact that β is definable implies, by lemma A.2, that there are only two possibilities for each set A_{ℓ} : either it contains some open set, or it is nowhere dense. Since when $\ell = n+1$ this set does not have full dimension, as shown in the previous paragraph, the first alternative cannot hold, so it must be nowhere dense. That is, its closure has an empty interior, which implies that $W_0 \setminus \operatorname{clos} A_{n+1}$ is a nonempty open set. Thus there is some open set V of $W_0 \subseteq \mathbb{R}^{m(n+1)}$ of the special product form $V = V_1 \times \cdots \times V_{n+1}$, for some nonempty connected open subsets V_1, \ldots, V_{n+1} of \mathbb{R}^m , so that $V \bigcap A_{n+1} = \emptyset$. Now let $Q \subseteq W_0^2 \subseteq \mathbb{R}^{2m(n+1)}$ be the open set defined as follows:

 $Q := V \times V.$

The claim is that $Q \cap S_{2n+2} = \emptyset$. To establish this fact, we take an arbitrary element

$$(u_1, \ldots, u_{n+1}, v_1, \ldots, v_{n+1})$$

of Q and show that it cannot be \pm -shattered; that is, there is some sequence $\vec{\varepsilon} = (\varepsilon_1, \ldots, \varepsilon_{2n+2}) \in \{-1, 1\}^{2n+2}$ for which neither $\vec{\varepsilon}$ nor $-\vec{\varepsilon}$ is assignable. Consider the following sequence:

$$\vec{\varepsilon} := (\underbrace{1, \ldots, 1}_{n+1}, \underbrace{-1, \ldots, -1}_{n+1})$$

Assume that there would exist some parameter vector *x* so that this vector is assigned:

$$\beta(x, u_i) > 0, i = 1, \dots, n+1, \beta(x, v_i) \le 0, i = 1, \dots, n+1.$$

Observe that, in particular, it holds that $\beta(x, \cdot) \neq 0$ for this x. For each i = 1, ..., n + 1, let

 $\gamma_i : [0, 1] \to V_i \subseteq \mathbb{R}^m$

be a continuous function so that

 $\gamma_i(0) = u_i$ and $\gamma_i(1) = v_i$.

(Recall that V_i is connected.) Since $\beta(x, \gamma_i(t))$ is a continuous function of t, we conclude that for each *i* there is some t_i so that $\beta(x, \gamma_i(t_i)) = 0$. Writing $w_i := \gamma_i(t_i)$, this says that $\vec{w} := (w_1, \ldots, w_{n+1}) \in A_{n+1}$, which contradicts the fact that $\vec{w} \in V_1 \times \cdots \times V_{n+1} = V$ and that *V* was picked so that it is disjoint from A_{n+1} . Thus $\vec{\varepsilon}$ is not assignable. If $-\vec{\varepsilon}$ would be assignable, we would have an *x* such that $\beta(x, u_i) \leq 0$ for i = 1, ..., n + 1 and $\beta(x, v_i) > 0$ for i = 1, ..., n + 1, and the same argument leads once more to a contradiction.

Remark 3.1. Observe that the definability property is used when proving that A_{n+1} cannot be dense. If instead one would pick, for instance, $\beta(x, u) = \sin(xu)$, the property is false. For this example, A_2 is the union of all the lines in \mathbb{R}^2 that pass through (0, 0) and have a rational slope (plus the *y*-axis), so A_2 in this case is a dense set with an empty interior.

Remark 3.2. As remarked during the proof, a stronger result is established. In particular, for each nonempty open subset $W \subseteq \mathbb{R}^m$, there is a nonempty open subset $Q \subseteq W^{2n+2}$ such that $Q \cap S_{2n+2} = \emptyset$. (Apply with $W_0 := W^{n+1}$.)

4 Discontinuous Responses _____

The main theorem requires that the response function β be analytic as well as definable. It is possible, however, to extend its validity to some other classes of responses, including those obtained by considering neural networks that use "heaviside" activation functions

$$H(v) = \begin{cases} 0 & \text{if } v \le 0\\ 1 & \text{if } v > 0 \end{cases}$$

as well as sigmoidal activations. Such responses are a particular case of a piecewise-analytic definable response, meaning a response that is described by a (possibly different) definable analytic function in each piece of a partition of the space of parameters and inputs. The partition in turn is assumed to be determined by the signs of a finite number of definable analytic functions. We now make this concept precise.

The map β : $\mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$ is a *piecewise-analytic definable* response if there is some integer *p* and there exist $p + 2^p$ analytic definable functions

 $\phi_1,\ldots,\phi_p:\mathbb{R}^n\times\mathbb{R}^m\to\mathbb{R}$

and

$$\{\psi_{\alpha}: \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}, \alpha \in \{0, 1\}^p\}$$

such that the following property holds: for each $(x, u) \in \mathbb{R}^n \times \mathbb{R}^m$, letting

$$\alpha(\mathbf{x},\mathbf{u}) := \left(H(\phi_1(\mathbf{x},\mathbf{u})), \ldots, H(\phi_p(\mathbf{x},\mathbf{u})) \right),$$

then

$$\beta(\mathbf{x}, \mathbf{u}) = \psi_{\alpha(\mathbf{x}, \mathbf{u})}(\mathbf{x}, \mathbf{u}).$$

(That is, in each of the components of the partition of the (x, u) space determined by the possible signs of the functions ϕ_i , β is expressed by an appropriate ψ_{α} .)

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Corollary 4.1. If β is piecewise analytic definable, then $\mu_{\beta} \leq 2n + 3$.

The proof will be based on the construction of an analytic definable response

$$\beta': \mathbb{R}^{n+1} \times \mathbb{R}^m \to \mathbb{R}$$

with the following property: if a given sequence $\vec{\varepsilon} = (\varepsilon_1, \ldots, \varepsilon_k) \in \{-1, 1\}^k$ is assignable to a sample $\vec{u} = (u_1, \ldots, u_k)$, with respect to the response β , then it is also assignable to the same sample with respect to the response β' . This means that if a sample \vec{u} is \pm -shattered with respect to β , then it is also \pm -shattered with respect to β' , so we have $\mu_{\beta} \leq \mu_{\beta'}$. By the main theorem we know that $\mu_{\beta'} \leq 2(n+1) + 1$, so the desired conclusion follows. We now show how to construct β' .

As a preliminary step, we establish a simple fact regarding the approximation of piecewise constant functions by sigmoidal combinations. We first introduce some additional notations. Given any vector $r = (r_1, \ldots, r_p) \in \mathbb{R}^p$, we let $\gamma(r) := (H(r_1), \ldots, H(r_p))$. Consider the function

 θ : $\mathbb{R}^p \times \mathbb{R}^{2^p} \to \mathbb{R} : (r, s) \mapsto s_{\gamma(r)}$

(where we are indexing the coordinates of $s \in \mathbb{R}^{2^p}$ by vectors $\alpha = (\alpha_1, \ldots, \alpha_p) \in \{0, 1\}^p$). Now let $\sigma : \mathbb{R} \to \mathbb{R}$ be the function $\sigma(v) = (1 + e^{-x})^{-1}$ and, denoting $\sigma_1 := \sigma, \sigma_0 := 1 - \sigma$, consider, for each positive real number ρ , the (definable and analytic) function:

$$\chi_{\rho} \colon \mathbb{R}^{p} \times \mathbb{R}^{2^{p}} \to \mathbb{R} \colon$$

$$(r, s) \mapsto \sum_{\alpha \in \{0,1\}^{p}} \sigma_{\alpha_{1}}(\rho^{2}r_{1} - \rho) \dots \sigma_{\alpha_{p}}(\rho^{2}r_{p} - \rho)s_{\alpha} \,. \tag{4.1}$$

Lemma 4.1. For each pair $(r, s) \in \mathbb{R}^p \times \mathbb{R}^{2^p}$,

$$\lim_{\rho \to \infty} \chi_{\rho}(\mathbf{r}, \mathbf{s}) = \theta(\mathbf{r}, \mathbf{s}) \tag{4.2}$$

and

$$\theta(\mathbf{r}, \mathbf{s}) = \mathbf{0} \Rightarrow \lim_{\rho \to \infty} (1 + \rho^2) \chi_{\rho}(\mathbf{r}, \mathbf{s}) = \mathbf{0}.$$
(4.3)

Proof. Observe that we can rewrite θ as follows:

$$\theta(\mathbf{r},\mathbf{s}) = \sum_{\alpha \in \{0,1\}^p} H_{\alpha_1}(\mathbf{r}_1) \dots H_{\alpha_p}(\mathbf{r}_p) \mathbf{s}_{\alpha} ,$$

where $H_1 := H$, $H_0 := 1 - H$. Thus the first conclusion of the lemma is an immediate consequence of the fact that $\lim_{\rho \to \infty} \sigma(\rho^2 r - \rho) = H(r)$ for each

 $r \in \mathbb{R}$. Now assume that (r, s) is such that $\theta(r, s) = s_{\gamma(r)} = 0$. This means that the term corresponding to the index $\alpha = \gamma(r)$ does not appear in the sum (cf. equation 4.1) defining $\chi_{\rho}(r, s)$. Fix any other index α ; we claim that

$$\lim_{\rho\to\infty}(1+\rho^2)\sigma_{\alpha_1}(\rho^2 r_1-\rho)\ldots\sigma_{\alpha_p}(\rho^2 r_p-\rho)=0$$

(from which the second conclusion will follow). Indeed, since $\alpha \neq \gamma(r)$, there must exist some $j \in \{1, ..., p\}$ for which $\alpha_j \neq H(r_j)$; fix one such j. If $\alpha_j = 1$, then $H(r_j) = 0$ means that $r_j \leq 0$, and therefore $(1+\rho^2)\sigma(\rho^2 r_j - \rho) \rightarrow 0$ as $\rho \rightarrow \infty$; since the other terms are bounded, it follows that their product converges to zero. If instead $\alpha_j = 0$, then $H(r_j) = 1$ means that $r_j > 0$, and thus $(1 + \rho^2)(1 - \sigma(\rho^2 r_j - \rho)) \rightarrow 0$ as $\rho \rightarrow \infty$; again since the other terms are bounded, the product goes to zero.

Equation 4.3 implies in particular that when $\theta(r, s) = 0$,

$$\chi_{\rho}(\mathbf{r},\mathbf{s})-\frac{1}{1+\rho^2}<0$$

for all ρ large enough. Together with equation 4.2, this means that

$$\operatorname{sign}\left(\chi_{\rho}(\mathbf{r}, \mathbf{s}) - \frac{1}{1 + \rho^2}\right) = \operatorname{sign}\theta(\mathbf{r}, \mathbf{s})$$

as $\rho \to \infty$, for each $(\mathbf{r}, \mathbf{s}) \in \mathbb{R}^p \times \mathbb{R}^{2^p}$.

We now prove corollary 4.1. Let β , ϕ_1, \ldots, ϕ_p , and the ψ_{α} 's be as in the definition of piecewise-analytic definable response. Denote $\Phi(x, u) := (\phi_1, \ldots, \phi_p)$ and let $\Psi(x, u) \in \mathbb{R}^{2^p}$ be the vector whose α th component is $\psi_{\alpha}(x, u)$. Then $\beta(x, u) = \theta(\Phi(x, u), \Psi(x, u))$. We define

$$\beta'((\rho, \mathbf{x}), \mathbf{u}) := \chi_{\rho}(\Phi(\mathbf{x}, \mathbf{u}), \Psi(\mathbf{x}, \mathbf{u})) - \frac{1}{1 + \rho^2}$$

Thus

$$\operatorname{sign} \beta'((\rho, x), u) = \operatorname{sign} \beta(x, u)$$

as $\rho \to \infty$, for each $(x, u) \in \mathbb{R}^n \times \mathbb{R}^m$. Now assume that the sequence $\vec{\varepsilon} = (\varepsilon_1, \ldots, \varepsilon_k) \in \{-1, 1\}^k$ is assignable to the sample $\vec{u} = (u_1, \ldots, u_k)$ with respect to the response β . This means that there is some parameter vector $x \in \mathbb{R}^n$ so that $\operatorname{sign}(\beta(x, u_i)) = \varepsilon_i$ for each $i = 1, \ldots, k$. For large enough ρ , then, also $\operatorname{sign}(\beta'((\rho, x), u_i)) = \varepsilon_i$ for all *i*, so we conclude that $\vec{\varepsilon}$ is also assignable to the same sample with respect to the response β' .

Remark 4.1. The bound 2n + 3 can be reduced to 2n + 1 provided that the classes of functions $\phi_i(x, \cdot)$ and $\psi(x, \cdot)$ are closed under scaling and translation (as is the case commonly when dealing with artificial neural networks, where these are affine functions and the parameters *x* correspond to the coefficients of linear combinations [weights] and constant term [bias]). In that case, the parameter ρ can be absorbed into the remaining parameters.

Appendix _

We first review some elementary facts regarding real-analytic geometry. If M is any (analytic, second-countable) manifold, by a σ -analytic subset Z of M we mean one that can be decomposed into a countable union of embedded analytic submanifolds; for such a set Z, we define dim Z as the largest dimension of a submanifold appearing in such a union. (The dimension is well defined, in the sense that it does not depend on the particular decomposition.)

Consider now any analytic map $\pi : M \to N$ between two manifolds. For each $y \in N$, the "fiber" $M_y = \{x \in M \mid \pi(x) = y\}$ provides an example of a σ analytic subset (and if M is connected, either $M_y = M$ or dim $M_y < \dim M$). Now take any σ -analytic subset Z of M. Then the image $\pi(Z)$ is a σ -analytic subset of N, having dim $\pi(Z) \le \dim Z$, and the following inequality holds:

$$\dim Z \le \dim \pi(Z) + \max_{y \in \pi(Z)} \dim \left[M_y \bigcap Z \right].$$
(A.1)

(This inequality is a simple consequence of stratification theory; it is proved in the appendix of Sontag 1996. Note, incidentally, that a strict inequality may hold, as illustrated by the case $M = \mathbb{R}^2$, $N = \mathbb{R}$, $\pi =$ projection on first factor, and Z = the union of the *x* and *y* axes.)

We prove the following fact, which is basically theorem 1 in Sontag (1996). (That theorem could also be applied more directly, but the slight generalization given here should be useful for other purposes.)

Lemma A.1. Let \mathbb{X} , \mathbb{U}_1 , ..., \mathbb{U}_ℓ be (analytic, second countable) manifolds, with dimensions n, m_1, \ldots, m_ℓ respectively, and each \mathbb{U}_i connected. Assume given ℓ analytic maps

$$\beta_i : \mathbb{X} \times \mathbb{U}_1 \times \cdots \mathbb{U}_i \to \mathbb{R}, \ i = 1, \dots, \ell$$

so that the following property holds for each $i = 1, ..., \ell$:

$$\forall \, \overline{\mathbf{x}} \in \mathbb{X}, \, \forall \, \overline{u}_1 \in \mathbb{U}_1, \, \dots, \, \forall \, \overline{u}_{i-1} \in \mathbb{U}_{i-1}, \, \exists u \in \mathbb{U}_i \text{ so that}$$

$$\beta_i \left(\overline{\mathbf{x}}, \, \overline{u}_1, \, \dots, \, \overline{u}_{i-1}, \, u \right) \neq \mathbf{0}.$$
 (A.2)

Let

$$\mathcal{G}_{\ell} := \{ (\mathbf{x}, \mathbf{u}_1, \dots, \mathbf{u}_{\ell}) \in \mathbb{X} \times \mathbb{U}_1 \times \dots \times \mathbb{U}_{\ell} \mid \beta_1(\mathbf{x}, \mathbf{u}_1) = \dots \\ = \beta_{\ell}(\mathbf{x}, \mathbf{u}_1, \dots, \mathbf{u}_{\ell}) = \mathbf{0} \}.$$

Then this is a σ -analytic set with

$$\dim {\mathcal G}_\ell \le n + \sum_{j=1}^\ell m_j - \ell$$
 .

Proof. Define $\mathcal{G}_i := \{(x, u_1, \ldots, u_i) \in \mathbb{X} \times \mathbb{U}_1 \times \cdots \times \mathbb{U}_i \mid \beta_1(x, u_1) = \cdots = \beta_i(x, u_1, \ldots, u_i) = 0\}$ for each $i = 1, \ldots, \ell$, and $\mathcal{G}_0 := \mathbb{X}$; we prove by induction on *i* that dim $\mathcal{G}_i \le n + \sum_{j=1}^i m_j - i$. For i = 0 the result holds, so we now assume it has been proved for *i* and show the case i + 1. Let

$$\pi: \mathbb{X} \times \mathbb{U}_1 \times \cdots \times \mathbb{U}_{i+1} \to \mathbb{X} \times \mathbb{U}_1 \times \cdots \times \mathbb{U}_i$$

be the projection on the first 1+i factors. Write $Z := \mathcal{G}_{i+1}$. Note that $\pi(Z) \subseteq \mathcal{G}_i$ by definition of these sets, so in particular it holds by inductive hypothesis that

$$\dim \pi(Z) \le n + \sum_{j=1}^{i} m_j - i.$$
 (A.3)

For each fixed $y = (\overline{x}, \overline{u}_1, ..., \overline{u}_i) \in \pi(Z), \pi^{-1}(y) \bigcap Z = \{\overline{x}\} \times \{\overline{u}_1\} \times \cdots \times \{\overline{u}_i\} \times Q$, where

$$Q_{(\overline{\mathbf{x}},\overline{u}_1,\ldots,\overline{u}_i)} := \left\{ u \in \mathbb{U}_{i+1} \mid \beta_{i+1}(\overline{\mathbf{x}},\overline{u}_1,\ldots,\overline{u}_i,u) = \mathbf{0} \right\}.$$

Property A.2 implies that dim $Q_{(\bar{x},\bar{u}_1,...,\bar{u}_i)} \le m_{i+1}-1$. Thus from equation A.1 and using equation A.3, we conclude that

$$\dim Z \le n + \sum_{j=1}^{i} m_j - i + m_{i+1} - 1 = n + \sum_{j=1}^{i+1} m_j - (i+1),$$

and the induction is complete.

Corollary A.1. Let $\beta : \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$ be analytic, and consider for any integer ℓ the set

$$A_{\ell} := \{ (u_1, \ldots, u_{\ell}) \mid \exists x \operatorname{st} \beta(x, \cdot) \neq 0, \beta(x, u_1) = \cdots = \beta(x, u_{\ell}) = 0 \}.$$

Then this is a σ -analytic set of dimension at most $n + \ell(m-1)$.

Proof. Let $\mathbb{X} = \{x \in \mathbb{R}^n \mid \beta(x, \cdot) \neq 0\}$; this is an open subset of \mathbb{R}^n and hence a submanifold. (If $\mathbb{X} = \emptyset$, there is nothing to prove.) Apply lemma A.1 with $\beta_i(x, u_1, \ldots, u_i) := \beta(x, u_i)$ (and all $\mathbb{U}_i = \mathbb{U}$); observe that property A.2 holds by definition of \mathbb{X} . Then dim $\mathcal{G}_{\ell} \leq n + \ell(m-1)$, and the same bound applies to its projection A_{ℓ} on the \mathbb{U} components.

Finally, we review several facts about exp-RA definable functions. This discussion is based on recent work in model theory due to Gabrielov, Van den Dries, Wilkie, and many others; see Macintyre and Sontag (1993) and Sontag (1996) for more details and extensive bibliographical references.

A restricted analytic (RA) function $\mathbb{R}^q \to \mathbb{R}$ is any function that is real analytic on some compact subset *C* of \mathbb{R}^q and is zero outside *C* (examples: the functions sin and cos, which equal sin and cos on $[-\pi/2, \pi/2]$ and are zero outside this interval). Formally, consider the structure

 $L = (\mathbb{R}, +, \cdot, <, 0, 1, \exp\{ f, f \in RA \}),$

and the corresponding language for the real numbers with addition, multiplication, and order, as well as one function symbol for real exponentiation and one for each restricted analytic function. An (exp-RA) definable set is any subset of \mathbb{R}^k defined by a first-order formula over L with k free variables. A definable function is a function $\beta : M \to N$ whose graph is a definable set in this sense, and where N and M are definable subsets of two spaces \mathbb{R}^{l_1} and \mathbb{R}^{l_2} , respectively. For example, any function obtained by compositions of rational operations and taking exponentials is definable, such as $1/(1 + e^{-x})$; also definable is the function $\arctan(x)$, because its graph is characterized by the formula " $y = \arctan(x)$ iff $-\pi/2 < y < \pi/2$ and $\sin(y) = x \cos(y)$." Notice that any set obtained from a function β by logical operations (such as the set A_ℓ in corollary A.1) is definable provided that β is definable. The following fact is a nontrivial consequence of the work in logic cited above; see precise references in Sontag (1996):

Lemma A.2. Let *S* be a definable subset of \mathbb{R}^q for some *q*. Then either *S* contains an open subset, or it is a finite union of connected embedded submanifolds of \mathbb{R}^q (and in particular is nowhere dense).

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